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**Small Area Estimation:
the EBLUP estimator using the CAR model**

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Abstract

This paper deals with small area estimates based on components-of-variance models and, in particular it shows an EBLUP estimator with spatially correlated random area effects taking into account the information provided by neighboring areas (Spatial EBLUP). Introducing spatial dependence through two unknown parameters is low-premium insurance against the concern (expressed by Freedman and Navidi, 1986) that an important explanatory variable may have been missed, or that the linear functional relationship is in fact more complicated. Moreover the estimator of Mean Squared Error of the Spatial EBLUP is presented.

The properties of proposed estimator are evaluated by applying it both to the results of the sample survey on the Life Conditions in Tuscany (Italy) and to the erosion data collected in the Rathbun Lake Watershed in Iowa.

Key words: small area estimation, spatial correlation, CAR model, Spatial EBLUP, lattice data.

1 Introduction

The demand of reliable statistics for small areas, when only reduced sizes of the samples are available, has promoted the development of statistical methods from both the theoretical and empirical point of view. In this perspective the model based methodologies allow for the construction of efficient estimators and their confidence intervals. These small area estimators have several fields of application: from the production of social data to the production of environmental data.

Small area models make use of explicit linking models based on random area-specific effects that account for between area variation beyond that is explained by auxiliary variables included in the model. Under this class of models,

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when only aggregate specific covariates are available, the Best Linear Unbiased Predictor (BLUP) is obtained under the assumption of uncorrelated random area effects (Fay and Herriot, 1979). Details about this predictor, and its empirical version (EBLUP), for small area parameters (total y_i , mean \bar{y}_i) can be found in Ghosh and Rao (1994), Rao (1999), Datta and Lahiri (2000) and Rao (2003). The EBLUP estimator borrows strength from other small areas. From this point of view the potentialities of Geographical Information System (GIS) as a tool for the compilation of statistics, particularly in the field of small area statistics, are large. For example, especially in most of applications on environmental data, the land use, the quote, the slope can be used as auxiliary information to estimate the mean in the small areas. The use of GIS is due to the implicit conviction that the data of neighboring areas are correlated and the correlation decays to zero as distance increases. This suggests that further improvement in the EBLUP estimator can be gained by including eventual spatial interaction between random area effects. Introducing spatial dependence through two unknown parameters is low-premium insurance against the concern (expressed by Freedman and Navidi, 1986) that an important explanatory variable may have been missed, or that the linear functional relationship is in fact more complicated.

The only attempt to generalize the Fay-Herriot model, considering correlated random area effects between the neighboring areas, has been made by Cressie (1991). In the context of U.S. census under-count, it was modeled a state adjustment factor using the basic area level model allowing spatial correlation between the random state effects under the Conditional Autoregressive (CAR) spatial model. In the context of U.S. census undercount, the adjustment factor for each small area was determined as a function of spatial correlation, but it was not associated with any area-specific measure of variability. Until now estimators of Mean Squared Error (MSE) of the EBLUP estimators under a spatial model have not been spelled out.

This papers considers an BLUP estimator with spatially correlated random area effects taking into account the information provided by neighboring areas through the Conditional Autoregressive (CAR) process (Spatial BLUP - Section 2). Its empirical version (EBLUP) is obtained and an estimator of its MSE is proposed . The article also proposes a procedure to estimate the variance components of the model using maximum likelihood or restricted maximum likelihood, combining the Nelder-Mead method with "scoring" algorithm (Section 3). The properties of various estimators are evaluated in Section 4 and 5 by analyzing both data from the survey on the Life Conditions in Tuscany and erosion data collected in the Rathbun Lake Watershed in Iowa. Conclusions can be found in Section 6, where, theoretical and applied advantages of the

methodology proposed here are summarized.

2 Spatial BLUP

Let θ be the $m \times 1$ vector of the parameter of inferential interest (small area total y_i , small area mean \bar{y}_i with $i = 1 \dots m$) and assume that the $m \times 1$ vector of the direct estimator $\hat{\theta}$ is available and design unbiased

$$\hat{\theta} = \theta + e \quad (1)$$

with e the vector of independent sampling errors with mean $\mathbf{0}$ and known diagonal variance matrix ψ . When all the small areas are sampled, it can be of interest to summarize the data of each small area and to refer the result to a location inside the area. Generally the location is the centroid of the small area itself. When this situation arises the sample data can be considered as lattice data. The spatial relationship among data at different locations is usually based on developing neighborhoods and the autocorrelation of locations within neighborhoods. The spatial dependence among small areas is introduced by specifying a linear mixed model with spatially correlated random effects for the θ parameter:

$$\theta = \mathbf{X}\beta + \mathbf{Z}\mathbf{v} \quad (2)$$

where \mathbf{X} is the $m \times p$ matrix of the area specific auxiliary covariates $\mathbf{x}_i = (x_{i1}, x_{i2}, \dots, x_{ip})$, β is the regression parameters vector $p \times 1$, \mathbf{Z} is a $m \times m$ matrix of known positive constants, \mathbf{v} is the $m \times 1$ vector of the second order variation. In general the behavior of spatial phenomena is often the result of a mixture of both first order and second order effects. First order effects relate to the variation in the mean value of the process in the space (a global or large scale trend). Second order effects result from the spatial correlation structure, or the spatial dependence in the process; in other words, the tendency for deviations in value of the process from its mean to follow each other in neighboring sites (local or small scale effects). Basically there are two approaches to describe the spatial second order variation: Simultaneously Autoregressive models (SAR) and Conditional Autoregressive models (CAR). These models produce spatial dependence in the covariance structure as a function of a neighborhood matrix \mathbf{W} and a fixed unknown spatial correlation parameter (Wall, 2004). The CAR model is very different from SAR model: the conditional model assumes that the probability of observing a particular value at a given site is a conditional probability, i.e. it depends on the value of Y in the neighborhood of the site. The SAR model states that the probability is a product of functions which can

not be interpreted as conditional probabilities.

In the economy of this paper the deviations from the fixed part of the model $\mathbf{X}\beta$ are the result of a conditional autoregressive process (Besag, 1974):

$$v_i | \{v_j \in N_i\} \sim (\rho \sum_{j \in N_i} w_{ij} v_j, \sigma_u^2) \quad (3)$$

where N_i represents a set of neighboring areas of the i -th area, parameter ρ is the spatial autoregressive coefficient and σ_u^2 is the variance. Combining (1) and (2), with \mathbf{e} independent of \mathbf{v} , the model with spatially correlated random area effects is:

$$\hat{\theta} = \mathbf{X}\beta + \mathbf{Z}\mathbf{v} + \mathbf{e}. \quad (4)$$

The error terms \mathbf{v} and \mathbf{e} have respectively $m \times m$ covariance matrices:

$$\mathbf{G} = \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \quad (5)$$

that is the Conditional Autoregressive (CAR) dispersion matrix, where \mathbf{I} is the $m \times m$ identity matrix, and

$$\mathbf{R} = \psi = \text{diag}(\psi_i). \quad (6)$$

Thus the covariance matrix of the $\hat{\theta}$ is:

$$\mathbf{V} = \mathbf{R} + \mathbf{Z}\mathbf{G}\mathbf{Z}^T = \text{diag}(\psi_i) + \mathbf{Z}\sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T. \quad (7)$$

The \mathbf{W} matrix describes the neighborhood structure of the small areas whereas ρ defines the strength of the spatial relationship among the random effects associated with neighboring areas. The spatial weight matrix represents the potential interaction between locations. One common way to do this is to define $w_{ij} = 1$ if region i shares a common edge or border with region j or 0 otherwise. So \mathbf{W} is the first-order neighbor proximity matrix and here ρ is called a spatial autoregression parameter. Again, in CAR model \mathbf{W} needs to be symmetrical and $(\mathbf{I} - \rho \mathbf{W})$ needs to be strictly positive definite to ensure the existence and symmetry of $\sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1}$ in the conditional scheme (Upton and Fingleton, 1985). This is guaranteed if $\rho \in (\frac{1}{\min(\lambda_i)}, \frac{1}{\max(\lambda_i)})$ where λ_i 's are the eigenvalues of matrix \mathbf{W} . There are other ways to define \mathbf{W} as restricting rows of the neighborhood matrix to sum to 1 or creating more elaborate weights as functions of the length of borders (Wall, 2004).

Under the model, the Spatial Best Linear Unbiased Predictor (Spatial BLUP)

estimator of θ_i is:

$$\begin{aligned} \tilde{\theta}_i^S(\sigma_u^2, \rho) &= \mathbf{x}_i \hat{\beta} + \mathbf{b}_i^T \{ \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \} \mathbf{Z}^T \times \\ &\times \{ \text{diag}(\psi_i) + \mathbf{Z} \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \}^{-1} (\hat{\theta} - \mathbf{X} \hat{\beta}) \end{aligned} \quad (8)$$

where $\hat{\beta} = (\mathbf{X}^T \mathbf{V}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{V}^{-1} \hat{\theta}$ and \mathbf{b}_i^T is $1 \times m$ vector $(0, 0, \dots, 0, 1, 0, \dots, 0)$ with 1 in the i -th position. The proposed predictor is obtained from Henderson 1975 results for general linear mixed models involving fixed and random effects. The Spatial BLUP is equal to the traditional BLUP under the random area specific effects model when $\rho = 0$.

The *MSE* of Spatial BLUP can be obtained, under the specified model, as indicated in Rao (2003). The $MSE[\tilde{\theta}_i^S(\sigma_u^2, \rho)]$, depending on two variance components (σ_u^2, ρ) , can be expressed as:

$$MSE[\tilde{\theta}_i^S(\sigma_u^2, \rho)] = g_{1i}(\sigma_u^2, \rho) + g_{2i}(\sigma_u^2, \rho) \quad (9)$$

where the first term $g_{1i}(\sigma_u^2, \rho)$ is due to the estimation of random effects and is of order $O(1)$ while the second term $g_{2i}(\sigma_u^2, \rho)$ is due to the estimation of β and is of order $O(m^{-1})$ for large m (Rao, 2003). The details of the calculation are reported in Appendix A.

3 Spatial EBLUP

The estimator $\tilde{\theta}_i^S(\sigma_u^2, \rho)$ depends on the unknown variance components σ_u^2 and ρ . Replacing the parameters with asymptotically consistent estimators $\hat{\sigma}_u^2, \hat{\rho}$, a two stage estimator $\hat{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})$ is obtained and is called Spatial EBLUP:

$$\begin{aligned} \hat{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho}) &= \mathbf{x}_i \hat{\beta} + \mathbf{b}_i^T \{ \hat{\sigma}_u^2 (\mathbf{I} - \hat{\rho} \mathbf{W})^{-1} \} \mathbf{Z}^T \times \\ &\times \{ \text{diag}(\psi_i) + \mathbf{Z} \hat{\sigma}_u^2 (\mathbf{I} - \hat{\rho} \mathbf{W})^{-1} \mathbf{Z}^T \}^{-1} (\hat{\theta} - \mathbf{X} \hat{\beta}) \end{aligned} \quad (10)$$

with $\mathbf{b}_i^T = (0, 0, \dots, 0, 1, 0, \dots, 0)$ with 1 referring to the i -th area. The expected value $E[\hat{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})]$ is finite, the estimator is unbiased for θ and $\hat{\sigma}_u^2, \hat{\rho}$ are any translation invariant estimators of σ_u^2 and ρ (Kackar and Harville, 1984).

The variance components σ_u^2 and ρ can be estimated either by Maximum Likelihood (ML) or Restricted Maximum Likelihood (REML) methods, assuming normality of the random effects, or by the method of fitting constants. The ML and the REML estimators can be obtained iteratively using the ‘‘Nelder-Mead’’ algorithm (Nelder and Mead, 1965) and the ‘‘scoring’’ algorithm in sequence. The use of these procedures one after the other is necessary because the log-likelihood function has a global maximum and some local maximums.

The ‘‘Nelder-Mead’’ method for the maximization of a function does not depend on the selected starting point and is computationally compact but not fully efficient: it achieves a point that is close to the global maximum. For this reason it is necessary to use the ‘‘scoring’’ algorithm, selecting as a starting point the maximum that has been obtained by the ‘‘Nelder-Mead’’ method. The log-likelihood function, its partial derivatives and the information matrix are described in Appendix B and C.

The ML and REML estimators are robust, as they produce acceptable results even under non-normal distribution of the random effects (Jiang, 1996).

The MSE of the Spatial EBLUP estimator appears to be insensitive to the choice of the estimators $\hat{\sigma}_u^2$ and $\hat{\rho}$ (Kackar and Harville, 1984). Given normality of random effects, an approximation to the $MSE[\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})]$ is:

$$MSE[\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})] \approx g_{1i}(\sigma_u^2, \rho) + g_{2i}(\sigma_u^2, \rho) + g_{3i}(\sigma_u^2, \rho) \quad (11)$$

where $g_{3i}(\sigma_u^2, \rho)$ is due to the estimation of the variance components, and it is obtained by following the results of Kackar and Harville (1984):

$$g_{3i}(\sigma_u^2, \rho) = tr \left\{ \left[\begin{array}{c} \mathbf{b}_i^T (\mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} + \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T (-\mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1})) \\ \mathbf{b}_i^T (\sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} + \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T (-\mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1})) \end{array} \right] \mathbf{V} \times \right. \\ \left. \times \left[\begin{array}{c} \mathbf{b}_i^T (\mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} + \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T (-\mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1})) \\ \mathbf{b}_i^T (\sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} + \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T (-\mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1})) \end{array} \right]^T \bar{\mathbf{V}}(\hat{\sigma}_u^2, \hat{\rho}) \right\}. \quad (12)$$

with $\mathbf{D} = (\mathbf{I} - \rho \mathbf{W})$ and $\bar{\mathbf{V}}(\hat{\sigma}_u^2, \hat{\rho})$ is the asymptotic covariance matrix of $\hat{\sigma}_u^2$ and $\hat{\rho}$. In practical application the estimator $\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})$ has to be associated with an estimator of $MSE[\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})]$. An approximately unbiased estimator of it is given by:

$$mse[\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})] \approx g_{1i}(\hat{\sigma}_u^2, \hat{\rho}) + g_{2i}(\hat{\sigma}_u^2, \hat{\rho}) + 2g_{3i}(\hat{\sigma}_u^2, \hat{\rho}) \quad (13)$$

if $\hat{\sigma}_u^2$ and $\hat{\rho}$ are REML estimators. Otherwise, if the ML procedure is used, the $mse[\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})]$ is given by

$$mse[\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho})] \approx g_{1i}(\hat{\sigma}_u^2, \hat{\rho}) - \mathbf{b}_{ML}^T(\hat{\sigma}_u^2, \hat{\rho}) \nabla g_{1i}(\hat{\sigma}_u^2, \hat{\rho}) + g_{2i}(\hat{\sigma}_u^2, \hat{\rho}) + 2g_{3i}(\hat{\sigma}_u^2, \hat{\rho}). \quad (14)$$

The term $\mathbf{b}_{ML}^T(\hat{\sigma}_u^2, \hat{\rho}) \nabla g_{1i}(\hat{\sigma}_u^2, \hat{\rho})$ is an extra term due to the bias of $g_{1i}(\hat{\sigma}_u^2, \hat{\rho})$ and is calculated in Appendix D. If this term is ignored, the use of ML estimators could lead to underestimation of the approximation of MSE.

4 Application 1: survey on Life Conditions in Tuscany

The region of Tuscany is divided into 10 provinces and 287 municipalities. Each province area is obtained by aggregating a varying number of municipalities. In order to analyze the local economic systems of the region, the territory has been officially divided into 43 sub-regions called Local Economy Systems (LESs). These areas are aggregations of municipalities but they are different from provinces. The main town of the region (Florence) is a separate LES. In this application the small area parameter of interest is the annual per-capita mean income for each LES in the year 2001. A map of the LESs of Tuscany and a description of them can be found in Appendix E.

The primary source of data is the survey on Life Conditions (LC) in Tuscany, which provides the survey estimates of per-capita mean income at region level. The survey on Life Conditions was carried out in 2002 in order to measure the life conditions and to collect data relating to household budgets in Tuscany (IRPET, 2004).

We evaluated the performance of our proposed Spatial EBLUP estimator, comparing it with the corresponding EBLUP estimator under the Fay-Herriot model, and the direct estimator under the LC sampling design. In the sample 40 out of the 43 LESs are represented. The distribution of the sample by LES is reported in Appendix E.

Our attempt to find a parsimonious model led to the choice of the following LES-level predictors: ageing index (x_1 - population over 64/ population under 15) and the percentage of employees in industry (x_2). Moreover, the neighborhood structure W is defined as follows: spatial weight, w_{ij} , is $1/(\text{distance})^2$ if distance between LES i and LES j is less than 30 Km and 0 otherwise. Regarding the sampling variances ψ_i , they are estimated through a Jackknife procedure (Verma, 2004). The estimated variance $\hat{\psi}_i$ is then treated as a proxy to ψ_i . As result the $mse[\hat{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho}, \hat{\psi}_i)]$ is greater than $mse[\tilde{\theta}_i^S(\hat{\sigma}_u^2, \hat{\rho}, \psi_i)]$.

Using $\mathbf{x} = \{x_1, x_2\}$, assuming that the random effects are the result of a conditional autoregressive process, ML and REML estimates of β , σ_u^2 and ρ , the resulting Spatial EBLUP estimates and their estimated MSE were calculated. The estimated spatial autocorrelation coefficient $\hat{\rho}$ is 73.49 (*s.e.* = 4.94) with the ML procedure and 73.18 (*s.e.* = 6.07) with the REML method: this suggests the existence of a strong spatial relationship considering that $\rho \in (-91.71, 76.24)$. For the non-sampled area, the Spatial EBLUP of θ_i is equal to $\mathbf{x}_i \hat{\beta}$. The estimated variance components are applied to the complete neighborhood structure to calculate the *mse* estimator for each small area.

Software to estimate the parameters (σ_u^2, ρ) and to perform the calculation

of the Spatial EBLUP and the EBLUP estimators was written by the authors in *R* environment.

In order to appreciate the results obtained with the introduction of spatial information, the EBLUP estimates, using the same covariates, are also computed. Figure 1 displays the maps of the Spatial EBLUP and EBLUP estimates of annual per-capita mean income for the LESs in Tuscany. The maps give a visual representation of the different estimates. The territorial distribution of our estimates appears to be more variable than that obtained with the traditional EBLUP. At a larger range (3,905 Euros vs. 3,755) there is a wider diversification of annual per-capita mean income per LES. Given the same explanatory variables, the result is due to the additional spatial information inserted in our estimator. This moderates the smoothing effect resulting from the application of the traditional EBLUP and makes the specific characteristics of the LES evident. This happens without losing precision in the estimates. Our estimator, in fact, is less variable in each small area. The coefficient of variation (CV) per LES is mainly about 6–8% for our estimator, while it is 8–10% for the EBLUP. The results are clear from Table 2, which shows the distribution of the CV of small areas for the estimators. Direct, EBLUP and Spatial EBLUP estimates of the annual per-capita mean income and their estimated standard errors are reported in Appendix E.

Inferences from model-based estimators refer to the distribution implied by the assumed model. Model selection and validation play an important role in model-based estimation, in fact if the assumed models do not perform a good fit to the data, the estimators will be model-biased and can lead to erroneous inferences.

An evaluation of our spatial model is performed by treating the standard residuals $r = \hat{\theta}^S(\hat{\sigma}_u^2, \hat{\rho}) - \mathbf{X}\beta / (\text{diag}(\mathbf{V}))^{1/2}$ as iid $N(0, 1)$. In particular, to check the normality of the standardized residuals r and to detect outlier r , a normal q-q plot is examined (Figure 2). It can be noted that there are few outliers r and that they correspond to neighboring medium-income level areas in the zona of Florence. Not other significant departures from the assumed model were observed. The Shapiro-Wilk W statistic gave a value of 0.959 for small area effects, yielding a p-value of 0.108, which suggests no evidence against the hypothesis of normality.

5 Application 2: survey on erosion level in Rathbun Lake Watershed

In 1999, an environmental health study for the Rathbun Lake Watershed was started by a team of researchers from Iowa State University and the Chariton Valley Resource Conservation and Development office. The Rathbun Lake Watershed covers more than 365,000 acres (147,710 ha) in six counties of Iowa (USA), and is divided into 61 sub-watersheds, with an average size of 5,800 acres (2,350 ha) each. One of the major objectives of the project was the estimation of the surface water pollution by sub-watershed. Since erosion on agricultural land is known to be a major component of water pollution as well as the major source for lake sedimentation, a survey was designed to estimate the amount of erosion delivered to streams in the watershed. In this application the small area parameter of interest is the average total erosion for each sub-watershed.

According to the sampling design and data collection methodology described in Opsomer *et al.* (2001), each small area (domain) has been divided in plots (total 2146), each plot has been sequentially labeled and a systematic sampling of plots has been selected. The fractional interval (Särndal *et al.*, 1992, p. 77) has been fixed in order to select four units from each small area (domain). Not all these 4×61 units have been included in the sample. From each domain a simple random sample of 3 units has been drawn. Then within each sub-watershed, three 160-acre (64 ha) plots were selected, as is showed in Figure 3, and a sample of 183 units was obtained. The final sample can be reasonably assimilated to a simple random sample from the domains and the sampling variance ψ_i at the domain level can be estimated by $\left\{ \left(1 - \frac{n_i}{N_i}\right) \frac{\hat{\sigma}_i^2}{n_i} \right\}$, where $n_i = 3$ and N_i is the number of plots in the i -th area (Opsomer *et al.*, 2003).

Auxiliary data at the sub-watershed level are required in order to apply an area level random effect model. For this application the land use and the topography data, that are considered major determinants of the erosion, were available. Data related to these factor were available for the study region in the form of digital elevation and land use classification coverages. An initial set of eight variables for a prediction model was constructed combining soil slope class and vegetation types. The variables which was used as predictors were: "0 to 9% Slope-Row Crop" and "9 to 18% Slope-Row Crop".

To implement a EBLUP estimator combined with a CAR model a neighborhood structure \mathbf{W} has to be defined for the 61 small area within the study region. The spatial weight matrix represents the potential interaction between locations. A general spatial weight matrix can be defined by a symmetric binary contiguity matrix, which can be generated from the topological information given by Geographical Information System (GIS) based on adjacency criteria:

the spatial weight, w_{ij} , is set 1 if area i shares an edge with area j and 0 otherwise.

Figure 4 displays the map of the Rathbun Lake Watershed with the Spatial EBLUP estimates for average erosion per acre in 17 small areas, which are the result of sub-watersheds grouping at higher hierarchical hydrological level. The value of the estimated spatial autocorrelation coefficient $\hat{\rho}$ is 0.156 ($s.e. = 0.021$) using the ML procedure and 0.160 ($s.e. = 0.022$) with the REML method, which suggests a strong spatial relationship considering that $\rho \in (-0.349, 0.171)$.

In order to assess the achieved results with the introduction of the spatial information in the small area estimation, the EBLUP estimator and the Direct estimator are also calculated. In Table 2 are reported the average of the estimated standard errors and its variability per acre of the Spatial EBLUP, the EBLUP and the Direct estimators. Table 2 shows also the average of the estimated mse per acre and its breakdown into g_1 , due to the random effects, g_2 , which accounts for the variability in the estimator $\hat{\beta}$ and g_3 due to estimate ρ and σ_u^2 .

The Spatial EBLUP method provides estimates with smaller average estimated standard errors than the Direct and the EBLUP estimators. We note that g_1 is lower for the Spatial EBLUP compared to that in the EBLUP, while g_2 and g_3 are larger than those of the EBLUP estimator. These results are motivated, respectively, by the precise fit of the correlated random effects model to the data (g_1) and by the additional estimation of parameter ρ that is not included in the model underlying the EBLUP estimator (g_2 and g_3). The estimates of the average erosion in each of the 61 small area are reported in Annex F.

An evaluation of our spatial model is performed by treating the standard residuals r . The Shapiro-Wilk W statistic gives a value of 0.976 for small area effects, yielding a p-value of 0.289 that suggests no evidence against the hypothesis of normality.

A simple exploratory device enables another evaluation of the model: the plotting of estimated random effects \hat{v} against $W\hat{v}$, which corresponds to an average of the estimated random effects for nearest neighbors (Figure 5a). It is interesting to confront this plot with an equivalent one (Figure 5b), where $W\hat{v}$ is defined as an average of "randomly chosen neighbors" (rather than near neighbors). If there is no spatial correlation in the area effects, then one would expect the slope of a least squares line fitted to the data not to be significantly different from zero. This is the case of the plot in Figure 5b: the comparison between plot (a) and (b) suggests that the random area effects are truly spatially correlated.

6 Final remarks

In this paper we have developed an indirect small area estimator based on a CAR spatial model. The proposed estimator performs very well when applied to the LS data and to the Rathbun Lake Watershed data.

The results of this study suggest that the proposed spatial small area estimator, which takes into account the spatial dimensions of the data modeling the spatial correlation between small area random effects, allows to obtain an appreciable improvement of the small area estimates. The results lead to small area estimates that are better than the usual EBLUP estimates. The point estimators (13) and (14) of MSE of the Spatial EBLUP generated by their three components g_1 , g_2 and g_3 are smaller than those of EBLUP estimator. We note that g_1 is lower for the Spatial EBLUP compared to that in the EBLUP. This result is motivated by the precise fit of the correlated random effects model to the data. Thus, considering the cases study, the use of the Spatial EBLUP methodology, which takes into account the CAR model in the small area estimation, reduces the confidence interval. Moreover, the methodology presented allows to make use of all the informative components of the survey data including the geographical ones.

Finally, in practical applications, some of the areas are much smaller than the others and it may occur that these areas of interest are not represented in the sample. Even in this case the Spatial EBLUP can be employed: it can be used the neighborhood structure of those areas which are represented in the sample to estimate the parameters σ_u^2 and ρ . For the area i -th with sample observation the Spatial EBLUP is applied; for the area i -th with non-sample observations, the Spatial EBLUP of θ_i is equal to $\mathbf{x}_i\hat{\beta}$. The estimated parameters are applied to the complete neighborhood structure to calculate the *mse* estimator for each small area.

The developments of the Spatial EBLUP can regard either theoretical work or empirical studies. For example we have considered only the estimation of population totals and means of continuous response variables, but most surveys involve other parameters of interest, such as counts and percentages when the response variable is discrete. Empirical studies are also important to gain further experience with the approach that we propose. It would be useful to verify the performance of the methods using more complex spatial contiguity matrices (Cliff and Ord, 1981; Dacey, 1965; Getis and Aldstadt, 2004).

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Estimate	Coefficients of Variation				Total
	4 – 6%	6 – 8%	8 – 10%	10 – 12%	
$\hat{\theta}^S(\hat{\sigma}_{u_{ML}}^2, \hat{\rho}_{ML})$	2	35	6	0	43
$\hat{\theta}(\hat{\sigma}_{u_{ML}}^2)$	2	16	24	1	43
$\hat{\theta}^S(\hat{\sigma}_{u_R}^2, \hat{\rho}_R)$	1	18	20	4	43
$\hat{\theta}(\hat{\sigma}_{u_R}^2)$	1	12	26	4	43

Table 1: Class distribution of coefficients of variation of small areas for EBLUP and Spatial EBLUP estimators.

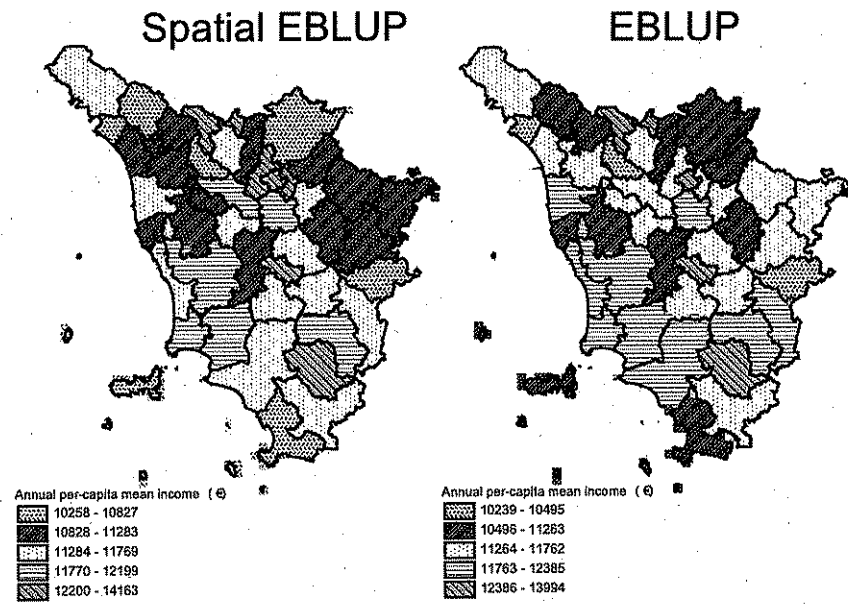


Figure 1: Map of the LESs of the region of Tuscany with Spatial EBLUP and EBLUP estimates for annual per-capita mean income.

Estimator	A.E.Se.	A.E.mse	A.E.(g ₁)	A.E.(g ₂)	A.E.(g ₃)
$\hat{\theta}^S(\hat{\sigma}_{u_{ML}}^2, \hat{\rho}_{ML})$	0.520	47.12	42.85	2.07	1.40
$\hat{\theta}(\hat{\sigma}_{u_{ML}}^2)$	0.549	52.38	47.88	2.57	0.93
$\hat{\theta}^S(\hat{\sigma}_{u_R}^2, \hat{\rho}_R)$	0.531	50.20	44.80	2.10	1.65
$\hat{\theta}(\hat{\sigma}_{u_R}^2)$	0.560	54.79	50.19	2.57	1.01
DIRECT θ	0.886	—	—	—	—

Table 2: Average of the Estimated Standard Errors (A.E.Se.) and average of the Estimated Mean Squared Error (A.E.mse.) of Spatial EBLUP, EBLUP and Direct estimators.

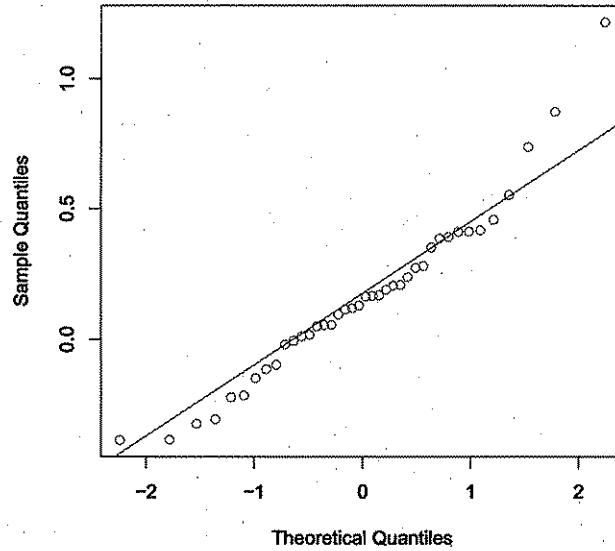


Figure 2: Normal q-q plot to check the normality of the standardized residuals r .

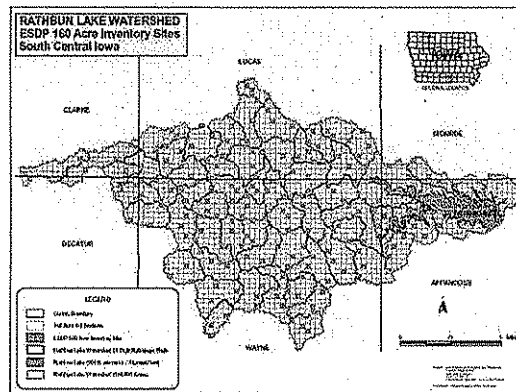


Figure 3: Map of Rathbun Lake watershed. Delineations within the watershed are the 61 sub-watersheds, and the dark squares are erosion assessment sample location.

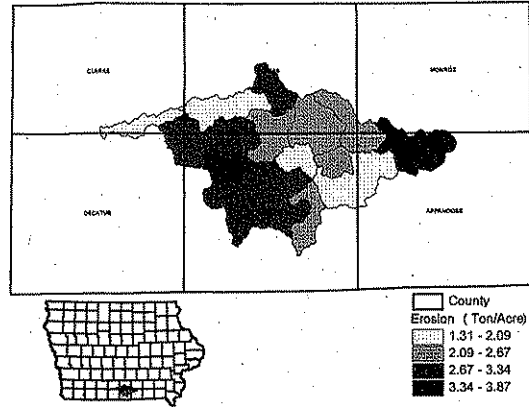


Figure 4: Map of Rathbun Lake watershed with Spatial EBLUP estimates for average erosion. ML procedure.

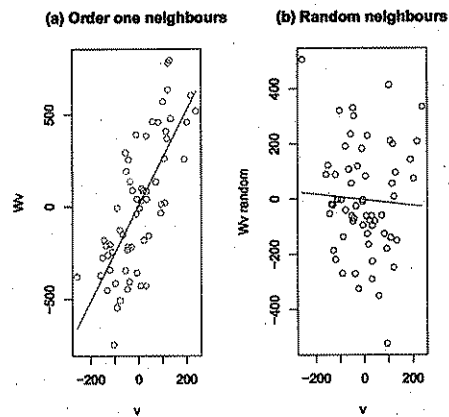


Figure 5: The estimated random effects \hat{v} against an average of estimated random effects for nearest neighbors $W\hat{v}$ (a) and an average of “randomly chosen neighbors” (b).

A Appendix

The $MSE[\hat{\theta}_i^S(\sigma_u^2, \rho)]$, depending on two parameters (σ_u^2, ρ) , can be expressed as:

$$MSE[\hat{\theta}_i^S(\sigma_u^2, \rho)] = g_{1i}(\sigma_u^2, \rho) + g_{2i}(\sigma_u^2, \rho) \quad (\text{A-1})$$

with with

$$g_{1i}(\sigma_u^2, \rho) = \mathbf{b}_i^T \{ \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} - \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \times \\ \times \{ \text{diag}(\psi_i) + \mathbf{Z} \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \}^{-1} \mathbf{Z} \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \} \mathbf{b}_i \quad (\text{A-2})$$

and

$$g_{2i}(\sigma_u^2, \rho) = (\mathbf{x}_i - \mathbf{b}_i^T \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \{ \text{diag}(\psi_i) + \mathbf{Z} \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \}^{-1} \mathbf{X}) \times \\ \times (\mathbf{X}^T \{ \text{diag}(\psi_i) + \mathbf{Z} \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \}^{-1} \mathbf{X})^{-1} \times \\ \times (\mathbf{x}_i - \mathbf{b}_i^T \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \{ \text{diag}(\psi_i) + \mathbf{Z} \sigma_u^2 (\mathbf{I} - \rho \mathbf{W})^{-1} \mathbf{Z}^T \}^{-1} \mathbf{X})^T. \quad (\text{A-3})$$

B Appendix

The log-likelihood function is:

$$l(\boldsymbol{\beta}, \sigma_u^2, \rho) = -\frac{1}{2} m \log 2\pi - \frac{1}{2} \log |\mathbf{V}| - \frac{1}{2} (\hat{\boldsymbol{\theta}} - \mathbf{X}\boldsymbol{\beta})^T \mathbf{V}^{-1} (\hat{\boldsymbol{\theta}} - \mathbf{X}\boldsymbol{\beta}) \quad (\text{B-1})$$

with \mathbf{V} as represented in (7) and the partial derivatives of $l(\boldsymbol{\beta}, \sigma_u^2, \rho)$ with respect to σ_u^2 and ρ given by

$$s_{\sigma_u^2}(\boldsymbol{\beta}, \sigma_u^2, \rho) = \frac{\partial l}{\partial \sigma_u^2} = -\frac{1}{2} \text{tr} \{ \mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \} + \frac{1}{2} (\hat{\boldsymbol{\theta}} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1}) (\hat{\boldsymbol{\theta}} - \mathbf{X}\boldsymbol{\beta}) \\ s_{\rho}(\boldsymbol{\beta}, \sigma_u^2, \rho) = \frac{\partial l}{\partial \rho} = -\frac{1}{2} \text{tr} \{ \mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 [\mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1}] \mathbf{Z}^T \} + \\ + \frac{1}{2} (\hat{\boldsymbol{\theta}} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 [\mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1}] \mathbf{Z}^T \mathbf{V}^{-1}) (\hat{\boldsymbol{\theta}} - \mathbf{X}\boldsymbol{\beta}) \quad (\text{B-2})$$

with $\mathbf{D} = (\mathbf{I} - \rho \mathbf{W})$. The matrix of expected second derivatives of $-l(\boldsymbol{\beta}, \sigma_u^2, \rho)$ with respect to σ_u^2 and ρ is given by

$$\mathcal{I}(\sigma_u^2, \rho) = \begin{bmatrix} \mathcal{I}_{11} & \mathcal{I}_{12} \\ \mathcal{I}_{21} & \mathcal{I}_{22} \end{bmatrix} \quad (\text{B-3})$$

where

$$\mathcal{I}_{11} = \frac{1}{2} \text{tr} \{ \mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \} \\ \mathcal{I}_{12} = \frac{1}{2} \text{tr} \{ \mathbf{V}^{-1} \mathbf{Z} \mathbf{C}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \}$$

$$\mathcal{I}_{21} = \frac{1}{2} \text{tr}\{\mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T\}$$

$$\mathcal{I}_{22} = \frac{1}{2} \text{tr}\{\mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T\}.$$

The ML estimators $\hat{\sigma}_{uML}^2$ and $\hat{\rho}_{ML}$ can be obtained iteratively using the “scoring” algorithm:

$$\begin{bmatrix} \sigma_u^2 \\ \rho \end{bmatrix}^{(n+1)} = \begin{bmatrix} \sigma_u^2 \\ \rho \end{bmatrix}^{(n)} + [\mathcal{I}(\sigma_u^2, \rho)]^{-1} \cdot s \left[\hat{\beta}(\sigma_u^2, \rho), \sigma_u^2, \rho \right] \quad (\text{B-4})$$

where n indicates the number of iteration.

C Appendix

The partial derivatives of the restricted log-likelihood function $l_R(\sigma_u^2, \rho)$ with respect to variance components are:

$$\begin{aligned} s_{R_{\sigma_u^2}}(\sigma_u^2, \rho) &= \frac{\partial l_R}{\partial \sigma_u^2} = -\frac{1}{2} \text{tr}\{\mathbf{P} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T\} + \frac{1}{2} \hat{\boldsymbol{\theta}}^T \mathbf{P} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{P} \hat{\boldsymbol{\theta}} \\ s_{R_{\rho}}(\sigma_u^2, \rho) &= \frac{\partial l_R}{\partial \rho} = -\frac{1}{2} \text{tr}\{\mathbf{P} \mathbf{Z} \sigma_u^2 [\mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1}] \mathbf{Z}^T\} + \\ &\quad + \frac{1}{2} \hat{\boldsymbol{\theta}}^T \mathbf{P} \mathbf{Z} \sigma_u^2 [\mathbf{D}^{-1} \mathbf{W} \mathbf{C}^{-1}] \mathbf{Z}^T \mathbf{P} \hat{\boldsymbol{\theta}} \end{aligned} \quad (\text{C-1})$$

with $\mathbf{P} = \mathbf{V}^{-1} - \mathbf{V}^{-1} \mathbf{X} (\mathbf{X}^T \mathbf{V}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{V}^{-1}$ and with $\mathbf{D} = (\mathbf{I} - \rho \mathbf{W})$.

The $\mathcal{I}_R(\sigma_u^2, \rho)$ matrix assumes the form:

$$\mathcal{I}_R(\sigma_u^2, \rho) = \begin{bmatrix} \mathcal{I}_{11} & \mathcal{I}_{12} \\ \mathcal{I}_{21} & \mathcal{I}_{22} \end{bmatrix} \quad (\text{C-2})$$

where

$$\mathcal{I}_{11} = \frac{1}{2} \text{tr}\{\mathbf{P} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{P} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T\}$$

$$\mathcal{I}_{12} = \frac{1}{2} \text{tr}\{\mathbf{P} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{P} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T\}$$

$$\mathcal{I}_{21} = \frac{1}{2} \text{tr}\{\mathbf{P} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{P} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T\}$$

$$\mathcal{I}_{22} = \frac{1}{2} \text{tr}\{\mathbf{P} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{P} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T\}.$$

Then the “Nelder-Mead” method and the “scoring” algorithm (B-4) are used and at convergence the REML estimators are obtained. The asymptotic covariance matrix of $\hat{\beta}_R$, $\hat{\sigma}_{uR}^2$ and $\hat{\rho}_R$ has a diagonal structure $\text{diag} \left[\bar{\mathbf{V}}(\hat{\beta}_R), \bar{\mathbf{V}}(\hat{\sigma}_{uR}^2, \hat{\rho}_R) \right] \approx \text{diag} \left[\bar{\mathbf{V}}(\hat{\beta}_{ML}), \bar{\mathbf{V}}(\hat{\sigma}_{uML}^2, \hat{\rho}_{ML}) \right]$ with

$$\bar{\mathbf{V}}(\hat{\beta}_R) \approx \bar{\mathbf{V}}(\hat{\beta}_{ML}) = (\mathbf{X}^T \mathbf{V}^{-1} \mathbf{X})^{-1}$$

$$\bar{\mathbf{V}}(\hat{\sigma}_{uR}^2, \hat{\rho}_R) \approx \bar{\mathbf{V}}(\hat{\sigma}_{uML}^2, \hat{\rho}_{ML}) = \mathcal{I}^{-1}(\sigma_u^2, \rho). \quad (\text{C-3})$$

D Appendix

If the ML procedure is used to estimate the variance components the term $\mathbf{b}_{ML}^T(\hat{\sigma}_u^2, \hat{\rho}) \nabla g_{1i}(\hat{\sigma}_u^2, \hat{\rho})$ of the MSE estimator of Spatial EBLUP is given by:

$$\mathbf{b}_i^T \left\{ \begin{aligned} & (\mathbf{D}^{-1} - [\mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} + \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T (-\mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1}) \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} + \\ & (\sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} - [\sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} + \\ & + \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1}]) \\ & \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T (-\mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1}) \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} + \sigma_u^2 \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1}]) \end{aligned} \right\} \mathbf{b}_i \quad (\text{D-1})$$

and

$$\mathbf{b}_{ML}(\sigma_u^2, \rho) = \frac{1}{2m} \left\{ \mathcal{I}^{-1}(\sigma_u^2, \rho) \left[\begin{array}{l} \text{tr}[(\mathbf{X}^T \mathbf{V}^{-1} \mathbf{X})^{-1} \mathbf{X}^T (-\mathbf{V}^{-1} \mathbf{Z} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1}) \mathbf{X}] \\ \text{tr}[(\mathbf{X}^T \mathbf{V}^{-1} \mathbf{X})^{-1} \mathbf{X}^T (-\mathbf{V}^{-1} \mathbf{Z} \sigma_u^2 \mathbf{D}^{-1} \mathbf{W} \mathbf{D}^{-1} \mathbf{Z}^T \mathbf{V}^{-1}) \mathbf{X}] \end{array} \right] \right\} \quad (\text{D-2})$$

where $\mathcal{I}(\sigma_u^2, \rho)$ is given by (B-3), $\mathbf{D} = (\mathbf{I} - \rho \mathbf{W})$.

E Appendix

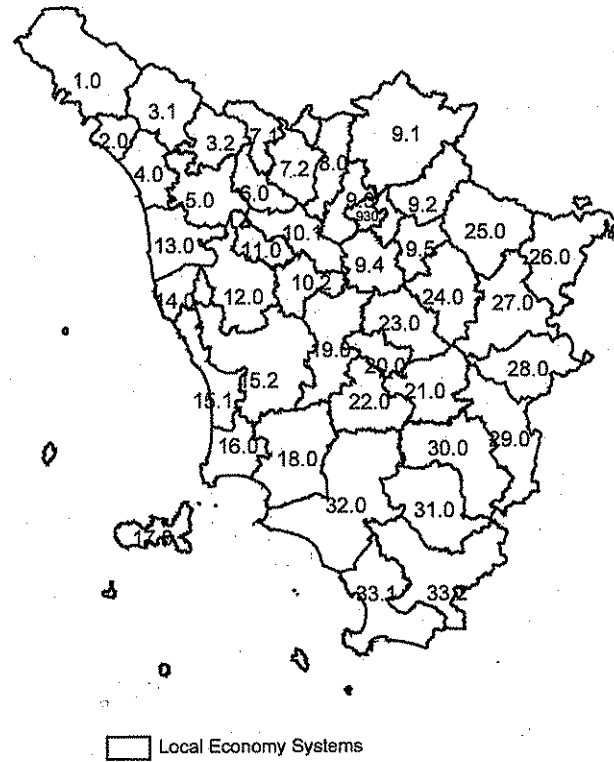


Figure E-1: Map of the LES of Tuscany.

<i>LES code</i>	<i>LES description</i>	<i>Sample size</i>
1	Lunigiana	44
2	Area di Massa-Carrara	144
3.1	Valle del Serchio - Quadrante Garfagnana	24
3.2	Valle del Serchio - Quadrante Media Valle	23
4	Versilia	99
5	Area Lucchese	113
6	Val di Nievole	109
7.1	Area Pistoiese - Quadrante Montano	-
7.2	Area Pistoiese - Quadrante Metropolitan	46
8	Area Pratese	117
9.1	Area Fiorentina - Quadrante Mugello	13
9.2	Area Fiorentina - Quadrante Val di sieve	10
9.3	Area Fiorentina - Quadrante Centrale	173
9.4	Area Fiorentina - Quadrante Chianti	76
9.5	Area Fiorentina - Quadrante Valdarno Superiore Nord	34
10.1	Circondario di Empoli - Quadrante empoese	81
10.2	Circondario di Empoli - Quadrante Valdelsano	26
11	Valdarno Inferiore	57
12	Val d'Era	61
13	Area Pisana	104
14	Area Livornese	69
15.1	Val di Cecina - Quadrante Costiero	35
15.2	Val di Cecina - Quadrante Interno	51
16	Val di Cornia	75
17	Arcipelago	-
18	Colline Metallifere	29
19	Alta Val d'Elsa	25
20	Area Urbana	47
21	Crete Senesi - Val d'Arbia	19
22	Val di Merse	16
23	Chianti	10
24	Valdarno Superiore Sud	43
25	Casentino	10
26	Alta Val Tiberina	56
27	Area Aretina	115
28	Val di Chiana Aretina	53
29	Val di Chiana Senese	53
30	Amiata - Val d'Orcia	50
31	Amiata Grossetano	-
32	Area Grossetana	108
33.1	Albegna-Fiora - Quadrante Costa d'Argento	39
33.2	Albegna-Fiora - Quadrante Colline Interne	45
930	Firenze	310

Table E-1: LES code and sample size, Tuscany.

<i>LES code</i>	θ_{ML}	<i>s.e.</i>	θ_{ML}^S	<i>s.e.</i>	θ_{REML}^S	<i>s.e.</i>	θ_{REML}	<i>s.e.</i>	Direct	<i>s.e.</i>
1	11768.79	837.46	11624.83	951.11	11626.38	938.50	11512.37	992.45	10167.49	1371.97
2	10257.92	649.92	10360.55	663.65	10206.44	678.05	10316.08	673.45	9938.32	741.38
3.1	10827.02	779.35	10859.42	929.00	10667.83	908.97	10730.42	987.45	8580.21	1596.80
3.2	10969.85	861.07	11109.03	989.74	10804.14	1009.70	10976.56	1050.30	8677.20	1763.12
4	10972.81	766.86	11423.12	870.03	11034.59	863.06	11461.78	907.06	11774.57	1201.40
5	11228.15	730.87	11540.03	814.09	11258.32	821.85	11554.48	846.34	11691.50	1084.32
6	10519.94	702.27	10238.74	715.54	10387.11	751.05	10164.98	732.36	9531.66	844.43
7.1	12797.61	1174.51	12938.85	1257.32	12733.47	1317.63	12888.73	1332.04	-	-
7.2	11487.80	874.28	11543.28	935.99	11464.00	999.21	11562.91	994.21	11899.10	1604.70
8	11111.78	739.60	11093.38	793.09	11092.00	816.30	11093.31	812.50	11074.33	952.47
9.1	10781.07	849.53	11187.55	1019.39	10804.10	997.89	11205.44	1104.18	11532.61	2904.06
9.2	11157.86	855.31	11262.88	1016.98	11155.44	1019.99	11251.72	1102.63	10600.48	3012.66
9.3	12648.86	704.12	11710.43	699.56	12639.37	758.57	11756.74	713.77	12063.35	808.79
9.4	12082.45	801.53	12088.28	911.23	12220.06	921.22	12192.04	959.91	13646.16	1406.75
9.5	11458.63	889.22	11435.75	1001.85	11540.81	1047.11	11487.48	1070.11	12587.11	1980.34
10.1	11857.39	796.28	11720.64	892.74	11886.05	892.93	11757.56	930.15	12240.36	1240.74
10.2	11759.01	899.31	11753.27	1075.98	11778.42	1020.43	11754.07	1147.15	12223.22	2284.77
11	11250.30	884.39	11363.73	977.87	11269.92	970.80	11374.65	1015.69	11579.70	1359.23
12	11198.00	814.10	11207.06	906.21	11184.70	910.07	11179.13	947.96	10859.71	1309.80
13	11688.44	805.81	12118.07	904.71	11847.04	908.24	12233.52	946.08	13550.35	1297.51
14	10932.57	755.27	10785.86	829.39	10877.84	834.21	10729.10	859.10	10067.99	1079.06
15.1	11726.21	809.98	12191.20	996.42	11859.57	957.52	12297.88	1075.86	15723.00	2433.36
15.2	12198.81	840.29	12384.70	979.65	12241.69	960.66	12400.34	1038.19	13007.86	1701.97
16	12102.65	816.06	12211.55	904.72	12081.15	902.62	12181.30	940.20	12022.66	1239.00
17	10621.41	963.58	10933.47	1133.52	10667.75	1084.41	10970.25	1200.62	-	-
18	11891.30	820.79	12046.34	1007.89	11911.26	943.96	12050.71	1079.42	12330.66	2119.80
19	11130.72	891.61	11093.33	969.04	11162.10	1069.75	11059.27	1033.54	10343.28	1805.38
20	13121.92	1043.36	13068.80	1063.26	13335.24	1433.50	13209.51	1135.22	17720.15	2288.80
21	11609.55	851.64	11762.20	993.50	11658.54	1026.40	11764.17	1072.37	12075.41	2410.07
22	11586.01	827.29	11573.28	986.87	11614.22	1016.61	11550.47	1067.04	10856.30	2450.98
23	11624.25	976.78	11336.27	1070.15	11811.39	1369.18	11402.75	1164.23	18190.08	5459.31
24	11184.55	846.58	11057.87	920.01	11171.50	962.03	11009.07	969.71	10323.60	1436.21
25	11259.04	866.89	11533.57	1024.72	11248.46	1006.31	11517.60	1110.73	11039.84	3131.57
26	11283.02	777.07	11469.42	881.99	11262.28	881.29	11435.54	928.51	11047.62	1334.14
27	11212.73	742.66	11689.11	800.54	11319.35	812.39	11744.98	829.17	12227.06	1034.10
28	10470.40	764.64	10495.40	844.29	10392.67	853.95	10414.44	881.32	9434.48	1168.40
29	11586.42	782.87	11856.36	912.75	11585.91	894.04	11849.33	964.83	11829.12	1462.18
30	12036.42	844.51	12139.25	958.32	11997.36	946.76	12097.72	1005.91	11747.44	1471.12
31	13058.41	1078.89	13044.94	1266.53	13003.45	1172.91	12999.81	1336.35	-	-
32	11530.45	762.63	11898.49	841.80	11649.68	849.18	11965.32	871.14	12559.21	1090.79
33.1	10612.06	866.16	10762.34	983.71	10579.28	968.83	10728.35	1027.67	9951.94	1438.63
33.2	11706.09	852.64	11463.72	953.11	11537.58	942.07	11335.25	990.95	9802.54	1329.82
930	14163.32	687.59	13994.07	693.81	14280.94	735.72	14121.33	704.92	15144.66	784.65

Table E-2: Direct, EBLUP and Spatial EBLUP estimates for annual per-capita mean income for each LES of the Tuscany region.

F Appendix

Area Code	$\hat{\theta}^S(\hat{\sigma}_{UR}^2, \hat{\rho}_R)$	s.q.m.	$\hat{\theta}(\hat{\sigma}_{UR}^2)$	s.q.m.	$\hat{\theta}$	s.q.m.
10280201040010	2.85	0.22	2.83	0.22	2.80	0.23
10280201040020	4.24	0.25	4.25	0.25	4.36	0.26
10280201040030	3.46	0.40	3.43	0.40	3.31	0.42
10280201040040	4.31	0.53	4.28	0.56	5.08	0.70
10280201040050	3.44	0.64	3.14	0.67	3.57	0.99
10280201040060	4.44	0.19	4.43	0.19	4.51	0.19
10280201040070	3.54	0.74	2.83	0.81	3.40	2.52
10280201040080	2.56	0.53	2.36	0.56	1.94	0.71
10280201040090	3.47	0.49	3.54	0.50	3.88	0.61
10280201040100	1.98	0.39	1.97	0.39	1.79	0.43
10280201040110	2.73	0.56	2.58	0.58	2.15	0.76
10280201040120	2.20	0.57	2.17	0.60	1.75	0.81
10280201040130	3.37	0.55	3.22	0.56	3.68	0.71
10280201040140	3.70	0.71	3.11	0.75	3.77	1.54
10280201040150	3.57	0.40	3.47	0.40	3.70	0.44
10280201040160	1.99	0.47	2.01	0.48	1.66	0.57
10280201040170	2.91	0.71	3.06	0.78	4.45	1.57
10280201040180	4.22	0.55	4.09	0.55	4.95	0.70
10280201040190	3.32	0.45	3.25	0.46	3.54	0.53
10280201040200	2.41	0.39	2.55	0.40	2.41	0.44
10280201040210	2.15	0.58	2.26	0.60	2.15	0.78
10280201040220	1.27	0.30	1.27	0.31	1.02	0.33
10280201040230	1.99	0.61	2.11	0.63	1.49	0.84
10280201040240	2.70	0.67	2.58	0.68	2.67	1.04
10280201040250	1.90	0.54	2.18	0.56	2.01	0.71
10280201040260	1.80	0.46	1.78	0.47	1.44	0.55
10280201040270	1.99	0.60	2.03	0.60	1.16	0.81
10280201040280	3.09	0.31	3.18	0.31	3.22	0.33
10280201040290	2.28	0.57	2.50	0.59	2.31	0.79
10280201050010	2.63	0.66	2.79	0.72	2.77	1.27
10280201050020	2.60	0.62	2.82	0.65	3.18	0.96

Table F-1: Estimate of the total watershed in each small area and estimated Standard Errors (E.Se.) of Spatial EBLUP, EBLUP and Direct estimators. REML procedure.

(Continued)

Area Code	$\hat{\theta}^S(\hat{\sigma}_{UR}^2, \hat{\rho}_R)$	s.q.m.	$\hat{\theta}(\hat{\sigma}_{UR}^2)$	s.q.m.	$\hat{\theta}$	s.q.m.
10280201060010	3.91	0.79	3.73	0.86	4.37	1.96
10280201060020	3.02	0.55	2.96	0.56	2.72	0.67
10280201060030	3.52	0.34	3.47	0.34	3.61	0.37
10280201060040	2.94	0.52	2.75	0.53	2.80	0.64
10280201060050	3.70	0.56	3.83	0.59	4.50	0.79
10280201060060	3.36	0.69	3.42	0.75	3.46	1.26
10280201060070	3.59	0.73	3.10	0.78	4.50	1.87
10280201060080	3.03	0.44	2.88	0.44	2.99	0.50
10280201060090	3.18	0.73	3.10	0.76	4.78	1.61
10280201060100	2.86	0.65	2.78	0.69	2.32	1.09
10280201060110	2.63	0.55	2.56	0.56	2.56	0.73
10280201060120	3.00	0.75	3.00	0.75	3.45	1.36
10280201060130	2.12	0.26	2.10	0.26	2.04	0.27
10280201060140	2.54	0.72	2.90	0.70	2.94	1.13
10280201060150	2.72	0.62	2.66	0.65	2.82	0.95
10280201060160	2.84	0.73	2.75	0.80	4.09	1.90
10280201060170	3.17	0.70	3.26	0.76	5.93	1.52
10280201060180	2.25	0.44	2.25	0.45	2.12	0.52
10280201060190	1.72	0.41	1.69	0.41	1.42	0.46
10280201060200	2.50	0.60	2.58	0.63	2.42	0.91
10280201060210	2.74	0.78	3.20	0.83	6.02	3.13
10280201060220	2.81	0.25	2.86	0.25	2.87	0.26
10280201060230	1.93	0.61	2.05	0.64	1.63	0.91
10280201060240	1.97	0.45	1.99	0.46	1.73	0.53
10280201060250	1.72	0.27	1.74	0.28	1.62	0.29
10280201070010	2.34	0.50	2.41	0.50	2.08	0.57
10280201070020	3.19	0.59	3.37	0.62	3.84	0.88
10280201070030	2.62	0.70	2.56	0.74	2.78	1.38
10280201070040	2.81	0.63	2.88	0.66	2.80	0.94
10280201070050	2.51	0.65	2.65	0.69	2.39	1.13

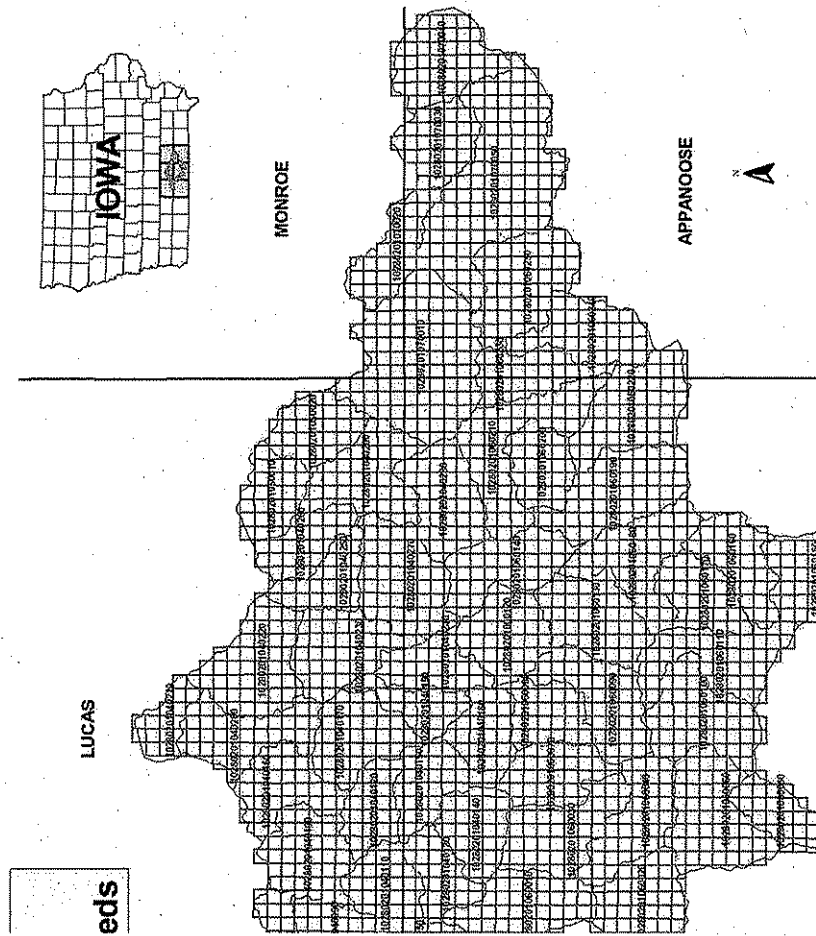


Figure F-1: Map of the area code in the Rathbun Lake Watershed

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